Joint Polar Satellite System (JPSS) Ground Project
Code 474
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Joint Polar Satellite System (JPSS)
Algorithm Specification Volume I:
Software Requirement Specification (SRS)
for OMPS Limb RDR

Block 2.0.0

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Joint Polar Satellite System (JPSS)
Algorithm Specification Volume I:
Software Requirement Specification (SRS)
for OMPS Limb RDR
JPSS Review/Approval Page

Prepared By:

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JPSS Ground System
(Electronic Approvals available online at https://jpssmis.gsfc.nasa.gov/frontmenu_dsp.cfm)

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Approved By:

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Preface

This document is under JPSS Ground Project configuration control. Once this document is approved, JPSS approved changes are handled in accordance with Class I and Class II change control requirements as described in the JPSS Configuration Management Procedures, and changes to this document shall be made by complete revision.

Any questions should be addressed to:

JPSS Configuration Management Office
NASA/GSFC
Code 474
Greenbelt, MD 20771

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## Change History Log

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<th>Effective Date</th>
<th>Description of Changes (Reference the CCR &amp; CCB/ERB Approve Date)</th>
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<td>This version incorporates 474-CCR-13-1177 which was approved by JPSS Ground ERB on the effective date shown.</td>
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<td>Oct 23, 2014</td>
<td>This version incorporates 474-CCR-14-2091 which was approved by the JPSS Ground ERB for CO10 on the effective date shown.</td>
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Introduction

The Joint Polar Satellite System (JPSS) is the National Oceanic and Atmospheric Administration's (NOAA) next-generation operational Earth observation program that acquires and distributes global environmental data primarily from multiple polar-orbiting satellites. The program plays a critical role in NOAA's mission to understand and predict changes in weather, climate, oceans and coasts, and the space environment, which support the Nation's economy and protect lives and property. The first JPSS satellite mission, the Suomi National Polar-orbiting Partnership (S-NPP) satellite, successfully launched in October 2011. S-NPP, along with the legacy NOAA Polar Operational Environmental Satellites (POES), provides continuous environmental observations. Two JPSS satellites will follow S-NPP: JPSS-1, planned for launch in fiscal year (FY) 2017, with JPSS-2 to follow in FY2021. In the future, the JPSS Polar Follow-On (PFO) provides for two additional missions, JPSS-3 and JPSS-4, as follow-on to the JPSS-2 mission to extend the JPSS Program lifecycle out to 2038.

In addition to the JPSS Program's own satellites operating in the 1330 (±10) Local Time of the Ascending Node (LTAN) orbit, NOAA also leverages mission partner assets for complete global coverage. These partner assets include the Department of Defense (DoD) Defense Meteorological Satellite Program (DMSP) operational weather satellites (in the 1730 - 1930 LTAN orbit), the European Organisation for the Exploitation of Meteorological Satellites (EUMETSAT) Meteorological Operational (Metop) satellites (in the 2130 LTAN orbit) and the Japanese Aerospace Exploration Agency (JAXA) Global Change Observation Mission-Water (GCOM-W) satellite (in the 1330 LTAN orbit). JPSS routes Metop data from McMurdo Station, Antarctica to the EUMETSAT facility in Darmstadt, Germany and EUMETSAT, in turn, provides Metop data to NOAA. For GCOM, JPSS routes the GCOM-W data from Svalbard, Norway to the NOAA Satellite Operations Facility (NSOF) in Suitland, MD, processes GCOM-W data and delivers GCOM-W products to the JPSS users who have JAXA permissions.

Additionally, the JPSS Program provides data acquisition and routing support to the DMSP and the WindSat Coriolis Program. JPSS routes DMSP data from McMurdo Station to the 557th Weather Wing at Offutt Air Force Base in Omaha, NE. After processing, the 557th releases the DMSP data for public consumption over the Internet via the National Geophysical Data Center in Boulder, CO. The JPSS Program provides data routing support to the National Science Foundation (NSF), as well as the National Aeronautics and Space Administration (NASA) Space Communications and Navigation (SCaN)-supported missions, which include the Earth Observing System (EOS). As part of the agreements for the use of McMurdo Station, JPSS provides communications/network services for the NSF between McMurdo Station, Antarctica and Centennial, Colorado.

As a multi-mission ground infrastructure, the JPSS Ground System supports the heterogeneous constellation of the before-mentioned polar-orbiting satellites both within and outside the JPSS Program through a comprehensive set of services as listed in Table 1-1.
Table: 1-1 JPSS Ground System Services

<table>
<thead>
<tr>
<th>Service</th>
<th>Description</th>
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<tbody>
<tr>
<td>Enterprise Management and Ground Operations</td>
<td>Provides mission management, mission operations, ground operations, contingency management and system sustainment</td>
</tr>
<tr>
<td>Flight Operations</td>
<td>Provides launch support and early orbit operations, telemetry and commanding, orbital operations, mission data playback, payload support, flight software upgrade, flight vehicle simulation, and disposal at the end of mission life</td>
</tr>
<tr>
<td>Data Acquisition</td>
<td>Provides space-ground communications for acquiring mission data</td>
</tr>
<tr>
<td>Data Routing</td>
<td>Provides routing of telemetry, mission and/or operations data through JPSS’ global data network</td>
</tr>
<tr>
<td>Data Product Generation</td>
<td>Provides the processing of mission data to generate and distribute raw, sensor, environmental, and auxiliary data products</td>
</tr>
<tr>
<td>Data Product Calibration and Validation</td>
<td>Provides calibration and validation of the data products</td>
</tr>
<tr>
<td>Field Terminal Support</td>
<td>Provides development and operational support to the Field Terminal customers</td>
</tr>
</tbody>
</table>

1.1 Identification

This volume documents the software used in the generation of Raw Data Record (RDR) algorithms for the Ozone Mapping and Profiler Suite Limb Sounder (OMPS Limb). It documents the OMPS Limb RDRs.

1.2 Algorithm Overview

The Ozone Mapping and Profiler Suite (OMPS) collects data to permit the calculation of the vertical and horizontal distribution of ozone in the Earth’s atmosphere. OMPS consists of separate nadir and limb sensors. The OMPS Nadir module consists of the Nadir Mapper and the Nadir Profiler sensors. When an OMPS Limb instrument is present, the OMPS measurements can be used to make (limb) ozone profile EDRs with high vertical resolution throughout the stratosphere. OMPS Limb instrument will not be flown on the JPSS-1 satellite but will be flown on the JPSS-2 satellite if provided by NASA. The JPSS ground processing software produces RDRs for OMPS Limb instrument (a.k.a. OMPS-L or OMPS LP RDRs) from the application packets received.

1.3 Document Overview

<table>
<thead>
<tr>
<th>Section</th>
<th>Description</th>
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<tbody>
<tr>
<td>Section 1</td>
<td>Introduction - Provides a brief overview of the JPSS Ground System and the relevant algorithm, as reference material only.</td>
</tr>
<tr>
<td>Section 2</td>
<td>Related Documentation - Lists related documents and identifies them as Parent, Applicable, or Information Documents such as, MOAs, MOUs, technical implementation agreements, as well as Data Format specifications. This section also establishes an order of precedence in the event of conflict between two or more documents.</td>
</tr>
<tr>
<td>Section 3</td>
<td>Algorithm Requirements - Provides a summary of the science requirements for the products covered by this volume.</td>
</tr>
<tr>
<td>Appendix A</td>
<td>Requirements Attributes - Provides the mapping of requirements to verification methodology and attributes.</td>
</tr>
</tbody>
</table>
2 Related Documentation

The latest JPSS documents can be obtained from URL: https://jpssmis.gsfc.nasa.gov/frontmenu_dsp.cfm. JPSS Project documents have a document number starting with 470, 472 or 474 indicating the governing Configuration Control Board (CCB) (Program, Flight, or Ground) that has the control authority of the document.

2.1 Parent Documents

The following reference document(s) is (are) the Parent Document(s) from which this document has been derived. Any modification to a Parent Document will be reviewed to identify the impact upon this document. In the event of a conflict between a Parent Document and the content of this document, the JPSS Program Configuration Change Board has the final authority for conflict resolution.

<table>
<thead>
<tr>
<th>Doc. No.</th>
<th>Document Title</th>
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<tbody>
<tr>
<td>470-00067</td>
<td>Joint Polar Satellite System (JPSS) Ground System Requirements Document (GSRD)</td>
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</table>

2.2 Applicable Documents

The following document(s) is (are) the Applicable Document(s) from which this document has been derived. Any modification to an Applicable Document will be reviewed to identify the impact upon this document. In the event of conflict between an Applicable Document and the content of this document, the JPSS Program Configuration Change Board has the final authority for conflict resolution.

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<thead>
<tr>
<th>Doc. No.</th>
<th>Document Title</th>
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2.3 Information Documents

The following documents are referenced herein and amplify or clarify the information presented in this document. These documents are not binding on the content of this document.

<table>
<thead>
<tr>
<th>Doc. No.</th>
<th>Document Title</th>
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<tr>
<td>474-00054</td>
<td>Joint Polar Satellite System (JPSS) Ground System (GS) Concept of Operations (ConOps)</td>
</tr>
<tr>
<td>470-00041</td>
<td>Joint Polar Satellite System (JPSS) Program Lexicon</td>
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3 Algorithm Requirements

3.1 States and Modes

3.1.1 Normal Mode Performance
Not applicable.

3.1.2 Graceful Degradation Mode Performance
Not applicable.

3.2 Algorithm Functional Requirements

3.2.1 Product Production Requirements
Not applicable.

3.2.2 Algorithm Science Requirements
Not applicable.

3.2.3 Algorithm Exception Handling
Not applicable.

3.3 External Interfaces

3.3.1 Inputs
Not applicable

3.3.2 Outputs

SRS.01.28_144 The OMPS Limb Profile RDR software shall generate the OMPS Limb Profile Science RDR from mission data packet APIDs specified in the JPSS Algorithm Specification Vol IV: SRSPF for OMPS Limb RDR (474-00448-04-28) <RDR><Science>.

Rationale: The Science RDR is one of OMPS LP RDR products and is generated from the specified mission data packet APIDs. APIDs associated with the Spacecraft Diary, as defined in the JPSS Algorithm Specification Vol IV: SRS Parameter File for Geolocation and Spacecraft Orientation (474-00448-04-08), are included in the deliverable RDR.

Mission Effectivty: S-NPP, JPSS-2

SRS.01.28_145 The OMPS Limb Profile RDR software shall generate the OMPS Limb Profile Diagnostic Calibration RDR from mission data packet APIDs specified in the JPSS Algorithm Specification Vol IV: SRSPF for OMPS Limb RDR (474-00448-04-28) <RDR><DiagCal>.
Rationale: The Diagnostic Calibration RDR is one of OMPS LP RDR products and is generated from the specified mission data packet APIDs. APIDs associated with the Spacecraft Diary, as defined in the JPSS Algorithm Specification Vol IV: SRS Parameter File for Geolocation and Spacecraft Orientation (474-00448-04-08), are included in the deliverable RDR.

Mission Effectivity: S-NPP, JPSS-2

SRS.01.28_146 The OMPS Limb Profile RDR software shall generate the OMPS Limb Profile Diagnostic Exposure #1 Earth View RDR from mission data packet APIDs specified in the JPSS Algorithm Specification Vol IV: SRSPF for OMPS Limb RDR (474-00448-04-28) <RDR><DiagExposEV_1>.

Rationale: The Diagnostic Exposure #1 Earth View RDR is one of OMPS LP RDR products and is generated from the specified mission data packet APIDs. APIDs associated with the Spacecraft Diary, as defined in the JPSS Algorithm Specification Vol IV: SRS Parameter File for Geolocation and Spacecraft Orientation (474-00448-04-08), are included in the deliverable RDR.

Mission Effectivity: S-NPP, JPSS-2

SRS.01.28_147 The OMPS Limb Profile RDR software shall generate the OMPS Limb Profile Diagnostic Exposure #2 Earth View RDR from mission data packet APIDs specified in the JPSS Algorithm Specification Vol IV: SRSPF for OMPS Limb RDR (474-00448-04-28) <RDR><DiagExposEV_2>.

Rationale: The Diagnostic Exposure #2 Earth View RDR is one of OMPS LP RDR products and is generated from the specified mission data packet APIDs. APIDs associated with the Spacecraft Diary, as defined in the JPSS Algorithm Specification Vol IV: SRS Parameter File for Geolocation and Spacecraft Orientation (474-00448-04-08), are included in the deliverable RDR.

Mission Effectivity: S-NPP, JPSS-2

SRS.01.28_148 The OMPS Limb Profile RDR software shall generate the OMPS Limb Profile Calibration RDR from mission data packet APIDs specified in the JPSS Algorithm Specification Vol IV: SRSPF for OMPS Limb RDR (474-00448-04-28) <RDR><Cal>.

Rationale: The Calibration RDR is one of OMPS LP RDR products and is generated from the specified mission data packet APIDs. APIDs associated with the Spacecraft Diary, as defined in the JPSS Algorithm Specification Vol IV: SRS Parameter File for Geolocation and Spacecraft Orientation (474-00448-04-08), are included in the deliverable RDR.

Mission Effectivity: S-NPP, JPSS-2

3.4 Science Standards

Not applicable.

3.5 Metadata Output

Not applicable.
3.6 Quality Flag Content Requirements
Not applicable.

3.7 Data Quality Notification Requirements
Not applicable.

3.8 Adaptation
Not applicable.

3.9 Provenance Requirements
Not applicable.

3.10 Computer Software Requirements
Not applicable.

3.11 Software Quality Characteristics
Not applicable.

3.12 Design and Implementation Constraints
Not applicable.

3.13 Personnel Related Requirements
Not applicable.

3.14 Training Requirements
Not applicable.

3.15 Logistics Related requirements
Not applicable.

3.16 Other Requirements
Not applicable.

3.17 Packaging Requirements
Not applicable.

3.18 Precedence and Criticality
Not applicable.
## Appendix A. Requirements Attributes

The Requirements Attributes Table lists each requirement with CM-controlled attributes including requirement type, mission effectivity, requirement allocation(s), block start and end, method(s) for verifying each requirement, etc.

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<th>Block End</th>
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<th>Block 2.1.0 VM</th>
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<td>RDR</td>
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<td>CGS</td>
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<td>F</td>
<td>RDR</td>
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<td>3.0.0</td>
<td>Inspection</td>
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<td>SRS.01.28_146</td>
<td>The OMPS Limb Profile RDR software shall generate the OMPS Limb Profile Diagnostic Exposure #1 Earth View RDR from mission data packet APIDs specified in the JPSS Algorithm Specification Vol IV: SRSPF for OMPS Limb RDR (474-00448-04-28) &lt;RDR&gt;&lt;DiagExposEV_1&gt;.</td>
<td>F</td>
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<td>Inspection</td>
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<td>F</td>
<td>RDR</td>
<td>S-NPP JPSS-2</td>
<td>CGS</td>
<td>2.0.0</td>
<td>3.0.0</td>
<td>Inspection</td>
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<tr>
<td>SRS.01.28_148</td>
<td>The OMPS Limb Profile RDR software shall generate the OMPS Limb Profile Calibration RDR from mission data packet APIDs specified in the JPSS Algorithm</td>
<td>F</td>
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